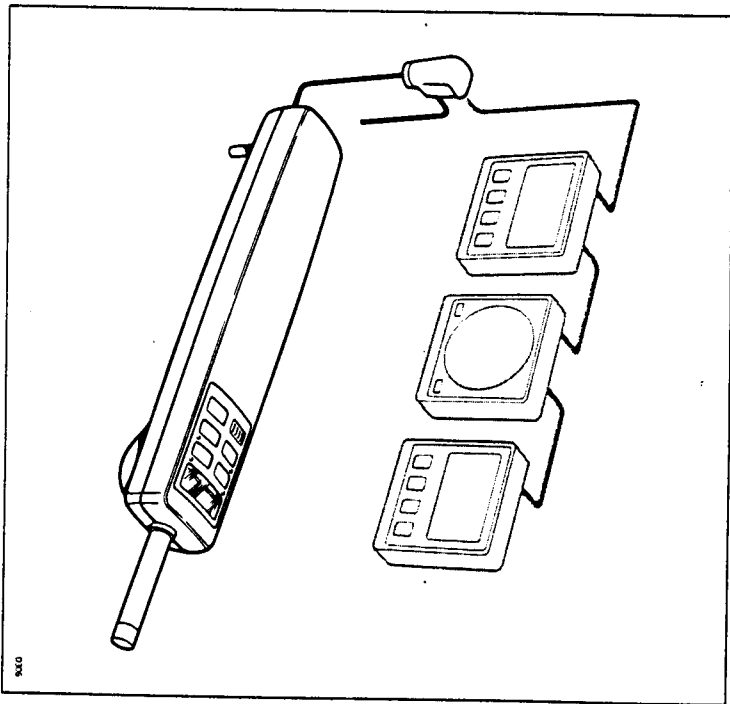


Distributed by

Any reference to Raytheon or RTN in this manual should be interpreted as Raymarine. The names Raytheon and RTN are owned by the Raytheon Company.



ST1000 Autopilot

100

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Specifications

- Power Supply
 - 10 to 15V d.c.
- Current consumption
 - Standby: 65mA (120mA with IIR)
 - Auto: between 0.5A and 1.5A depending on sailing conditions
- Operating temperature
 - 0°C to +70°C
- 6 button digital keypad
- LCD display of heading, locked course, speed, wind speed and direction
- User calibration for optimum performance
- Wind trim control in wind vane mode
- SeaTalk compatible
- Automatic compass deviation correction
- Northerly/Southerly heading compensation
- Automatic heading deadband
- Automatic tack
- Built-in radio navigation interface
- Waypoint advance feature

Safety

Passage making under autopilot can greatly voyage and ensure the crew can relax. However, dangerous lack of attention to basic seamanship should always be observed:

- Maintain a permanent watch and check re vessels and obstacles to navigations. No appear a dangerous situation can develop
- Maintain an accurate record of the vessel's radio navigation receiver or visual bearing
- Maintain a continuous plot of position on a locked autopilot heading steers you clear allowance for Tidal Set – the autopilot cannot
- Even when your autopilot is locked to the d navigation receiver maintain a log and a re navigation signals can produce significant stances and the autopilot cannot detect thi
- **Ensure that all members of crew are fully aware of the dangers required to disengage the autopilot**

Your Autohelm ST1000 will add a new dimension. However, it is the responsibility of the skipper to ensure the vessel at all times by careful observance of

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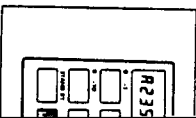
1.2 Operator controls

Standby



- Push to disengage the previous Auto key (s) In 'Standby'

Auto



- Push to engage In 'Auto' the display will show the heading for any real heading (e.g. 0000)
- Push and hold The previous heading, and 10 seconds. Also see 'Doc'

Dodge

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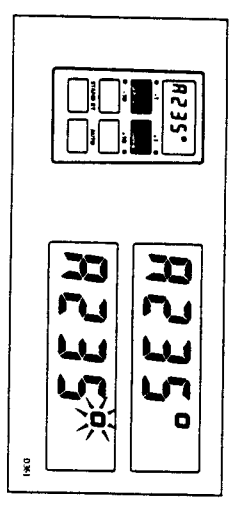


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Alterna
examp

Automatic Deadband Control (Auto seastate)



- Press the **+1** and **-1** degree course change keys together to toggle between auto deadband and fixed minimum deadband. The degree sign will flash when the fixed minimum dead band is selected

This can only be done with the Autopilot in 'Auto' mode.

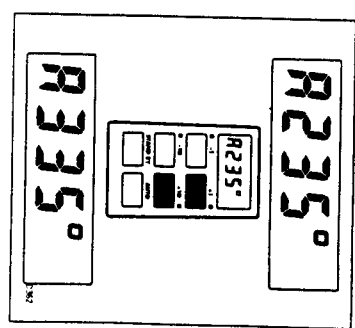
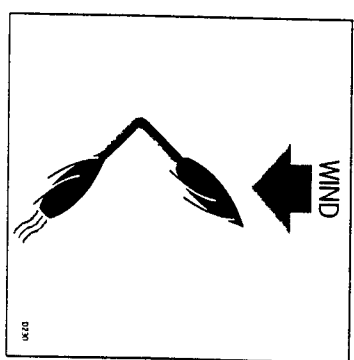
'Automatic deadband' (Auto seastate) will cause the pilot to gradually neglect repetitive movements of the vessel and only respond to true variations in course. This provides the best compromise between power consumption and course keeping accuracy by neglecting unnecessary rudder movements.

'Minimum deadband' will always provide the tightest course keeping possible but at the expense of increased power consumption and drive unit activity.

Automatic Tack (Autotack)

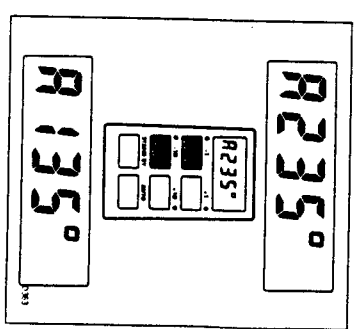
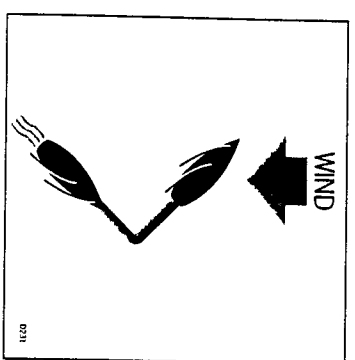
The ST1000 has a built in automatic tack facility which will turn the vessel through 100° in the required direction. This feature is available in both compass and vane modes.

- Press the **+1** and **+10** degree keys together to Tack through 100° to starboard



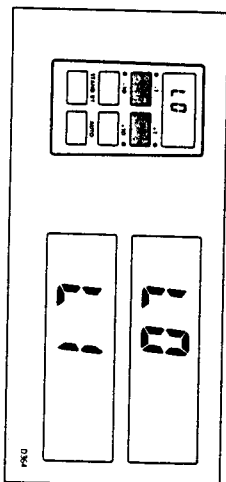
Or:

- Press the **-1** and **-10** degree keys together to Tack through 100° to port



Illumination

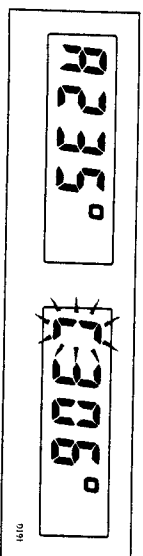
Illumination for the control head display can be switched on for night time viewing. This can only be done with the autopilot in 'Standby' mode



- Press the **+1** and **-1** keys together to toggle illumination on and off
- Also if other SeaTalk instruments or autopilot control units are connected to the SeaTalk bus the illumination on the ST1000 can be switched on or off from these units.

Off Course Alarm

The off course alarm will sound if the locked autopilot heading and the vessel's current heading differ, for greater than 20 seconds, by more than the value set in calibration level 6.



To cancel the off course alarm push **Standby** to return to hand steering. If the off course alarm sounds it is usually an indication that the vessel is carrying too much sail, or that the sails are badly balanced. In this case a significant improvement in course keeping can usually be obtained by improving sail balance.

1.3 Operating hir

Autopilot Oper

ator

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 Calibration Level 11 (Current Vessel Latitude) 33

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Advanced operation

The ST1000H for most type steering systems ST1000 can handle the pilot do

- The boat approach headings in
- You wish to
- You operate
- You wish to

The ST1000 is such as a GPS tidal streams and can also be made

'Advanced Operation' comprehensive supervisory menu include other S

Chapter 2: Using 'Track Control'

2.1 Operation in 'Track Control'

'Track Control' allows the points entered on a GPS

Operating hints

The Autopilot can receive the following sources:

- ST50 Navdata
- ST50 Navcenter

- ST6000 Autopilot Control
- ST7000 Autopilot Control
- SeaTalk Interface Box

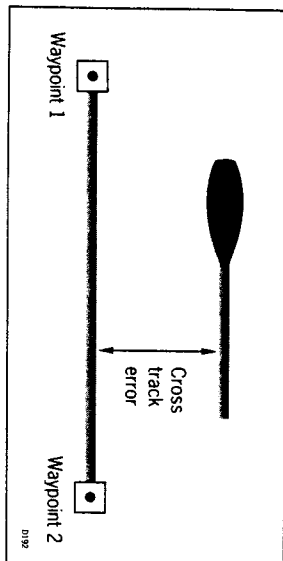
Note: All of the above must be set to the NMEA 0183 course changes which will automatically compensate

When initiating 'Track Control' the following ways:

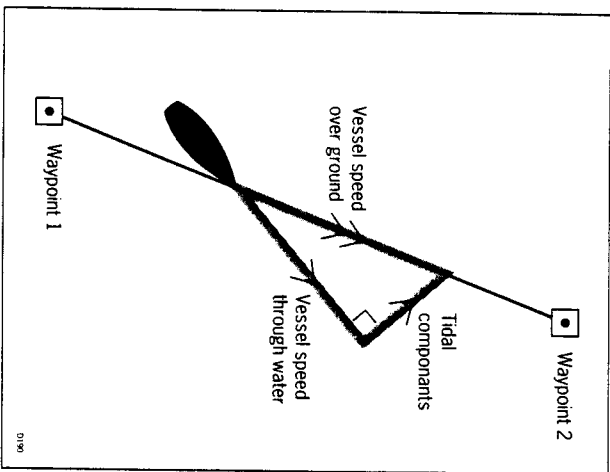
- Automatic acquisition (Waypoint data required)
- Manual acquisition (NMEA required only)

Manual acquisition is achieved by bringing the vessel to track and then bringing the vessel to the waypoint. The pilot is then instructed to enter 'Auto' and then press 'Track Control'. The vessel will then initiate 'Track Control'. The vessel will then be in 'Track Control' and the locked pilot has the vessel on track. Automatic acquisition can be initiated as follows:

- Bring the vessel to within 0.5 degrees of the waypoint
- Press **Auto**
- Press **+10** and **-10** degrees



Tidal Stream Compensation



Under most conditions 'Track Control' will hold the selected track to within $\pm 0.05m$ (300ft) or better.

The autopilot takes account of vessel speed when computing course changes to ensure optimum performance over a wide range of vessel speeds. If an Autohelm ST50 Speed or Tridata instrument is connected to the SeaTalk bus the control head will use measured vessel speed, otherwise the cruise speed entered during calibration level 5 will be used.

Waypoint Advance

If your navigation receiver transmits valid 'Waypoint Number' and 'Bearing to Waypoint' NMEA headers it is possible to advance from one waypoint to

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steer back towards

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computed position
reckoned position f
distance logged. In
more frequent in co
Local variations in r
produce deviations
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careful navigation**

2.2 Operation in W

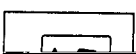
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Chapter 4: Autopilot re-calibration

The ST1000 can be adjusted to meet and steering system.

The calibration routine allows the following from their factory default settings.

- Rudder gain (Value on power up)
- Off course alarm limit
- Northerly/Southerly turning error

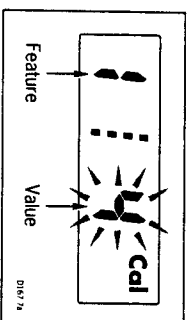
The autopilot also requires certain off

- Average cruise speed
- Local variation

This section will look at each feature in to suit your particular boat.

4.1 Entering calibration mode

- Press the **Standby** button for 5 seconds



The number on the left identifies the feature on the right the selected value for that feature.

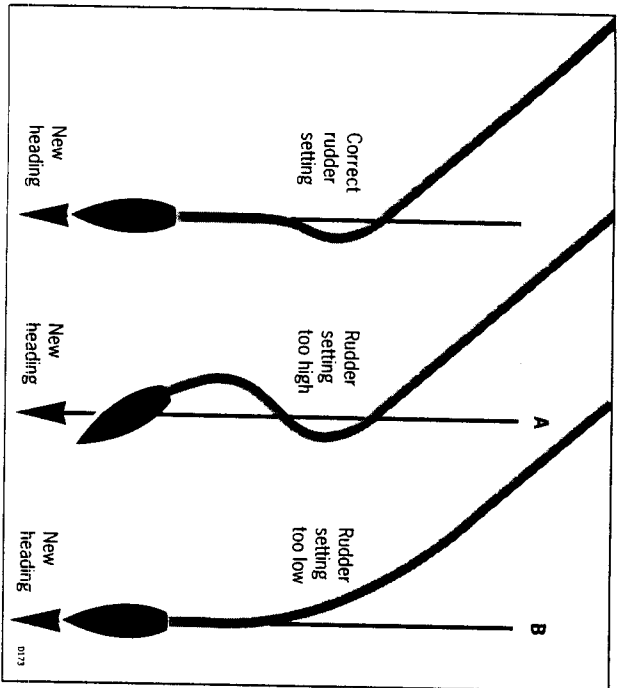
Each feature can be cycled through using the

The existing values can be viewed at any momentary push of the **Standby** key while in operating mode without affecting the present

Note: If on entering calibration the display



Please refer to 'Disabled calibration access' how to adjust.



These actions are most easily recognised in calm sea conditions where wave action does not mask basic steering performance.

Refer to chapter 4: 'Autopilot re-calibration', for instructions on how to adjust the rudder gain setting.

Repeat the test until a crisp course change with no more than 2° to 5° of overshoot is achieved.

The rudder control setting is not over critical and should be set to the lowest setting consistent with accurate course keeping. This will minimise actuator movements and hence reduce power consumption and wear and tear generally.

Similarly, an insufficient rudder control setting will result in understeer which gives sluggish steering performance (B). If the vessel takes a long time to make the turn and there is no overshoot then the rudder setting is too low.

4.2 Exiting calibration mode

You can exit calibration at any time in one of the following ways:

- Press **Standby** for 1 second
This will enter any adjusted values into memory.
- Momentarily press **Standby**
This will exit calibration without entering any adjusted values.

4.3 Suggested initial calibration settings

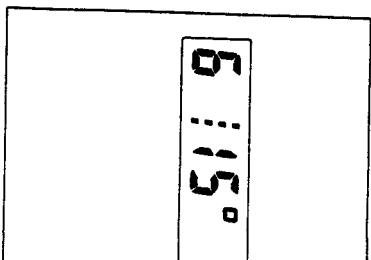
Listed below are suggested initial calibration settings for safe performance for the initial sea trial.

If you change any of the settings you can record the new values in the 'Values' column for future reference.

Feature Number	Feature	Set Value
1	Rudder gain	5
5	Average cruise speed	8
6	Off course alarm angle	20
9	Local magnetic variation	Off
10	North/South turning error correction	Off
11	Current vessel latitude	xx

Note:

1. Levels 2,3,4,7,8,12 and 13 are not available
2. If level 10 is set to 0 then level 11 will be omni



Calibration level 9 (Magnetic vari

Calibration level 9 tells the p
the boat's current position.

- Press the **Auto** key



You should enter your local v
value will then be transmitted
SeaTalk instruments such as

Note: - ve variation: East

+ve variation: West

Calibration level 10 (Northerly / S

Calibration level 10 allows No
to be switched in.

It may be noticed that the aut
northerly headings in the high
conversely southerly headings
by the increasing angle of dip
latitudes which has the effect
(southerly) headings. This erro
worse the further away from th

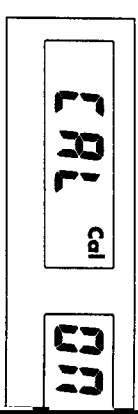
The ST1000 is able to compen
keeping on all headings by aut
depending on heading.

4.5 Disabled calibration access

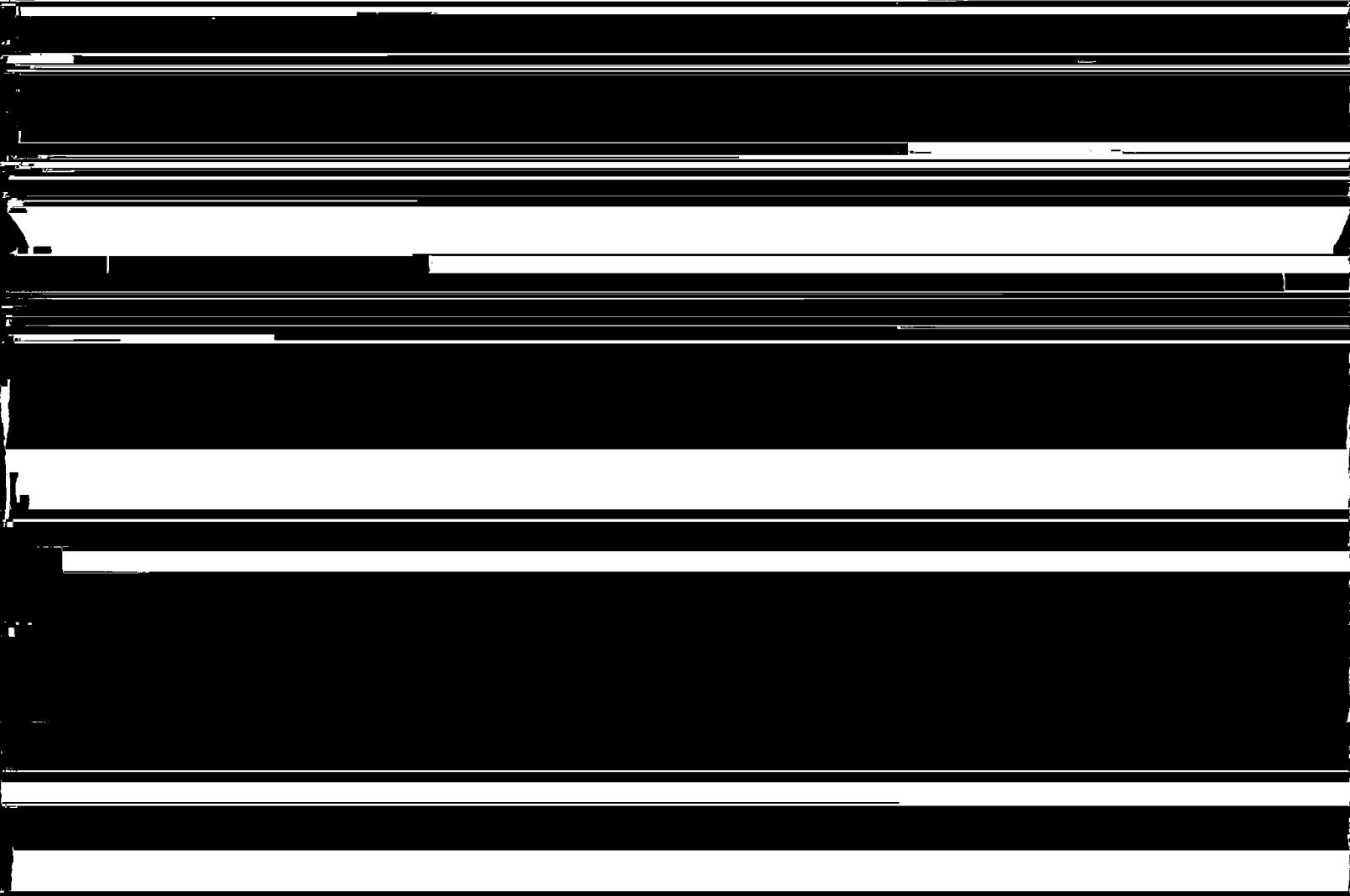
It is possible to disable the calibration set access.

This is achieved as follows:

- Press and hold the **-1** and **Standby** keys shows:



- Toggle the calibration access on and off using the **-1** key.
- Store the setting by pressing the **-1** and **Standby** keys until the control head returns to normal operation. If preferred this page can be removed from the display by pressing the **Standby** key. The setting has been switched off.



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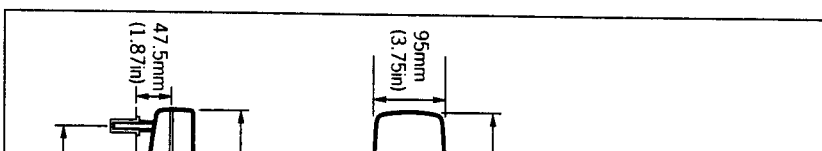
Chapter 5: Installation

Introduction

The autopilot is mounted on the yacht's system the unit

Since the autopilot is mounted on the yacht's system the unit is advisable to be at least 750mm

For correct installation



Dimension A =
mounting socket

Clamp the
A is meas
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shown.



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the port has
shown for

Note: The
be covered

5.1 Basic installation

After estab
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Proceed as

Tiller pin (cat no DC

- Drill 6mm
- Using a t
- Position

5.2 Installation Accessories

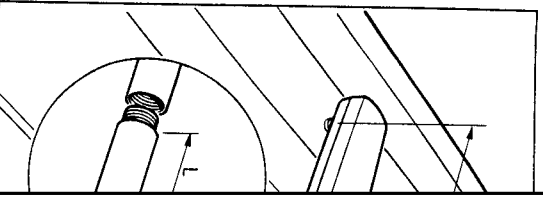
If it is not possible
seat/tilter as desc
will ensure a perfe

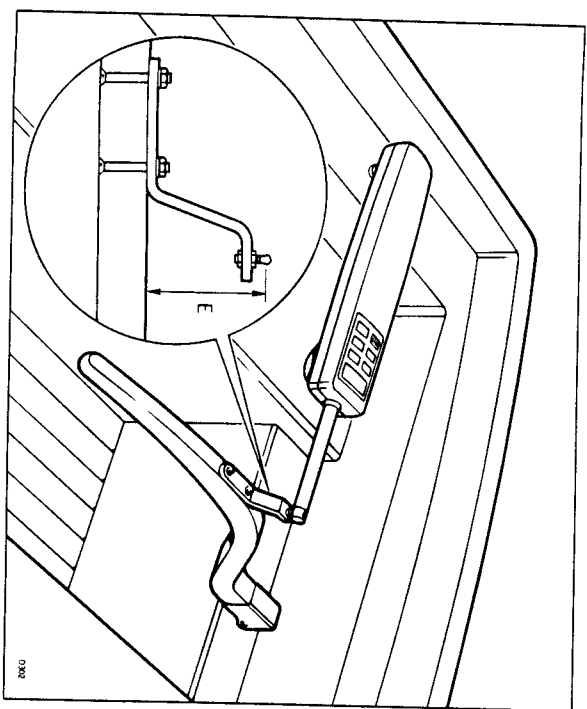
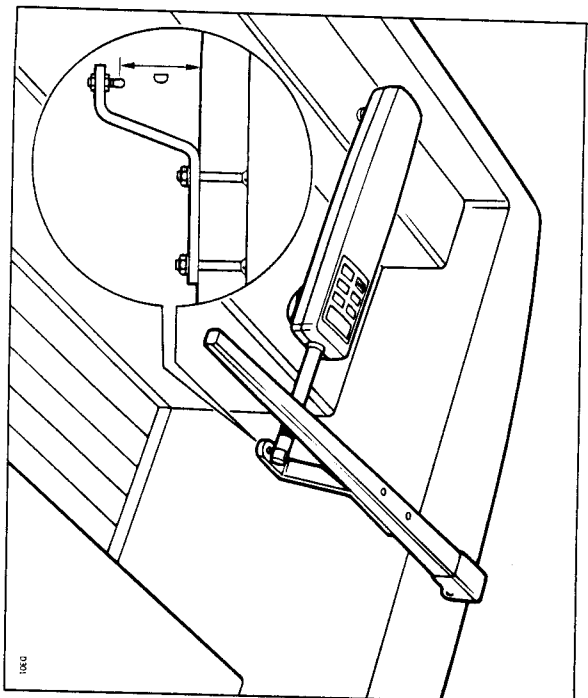
Pushrod extensions

The pushrod length
pushrod extension

Dimension C

589mm (23.2in)
615mm (24.2in)
640mm (25.2in)
665mm (26.2in)
691mm (27.2in)
716mm (28.2in)
742mm (29.2in)





Cantilever mount

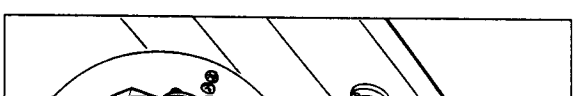
Where the cockpit The main can be

Installation

- Clamp
- Measure
- Refer to check

Dimensions

- 654mm
- 705mm
- 743mm
- 806mm
- 832mm



- Cut ca
thread
 - Remove
 - Tempc
mount
 - Ensure
mount
 - Mark a
 - Mount
washer
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 - Screw
 - Rough
 - Apply th
place th
 - Ensure
 - Allow th
- When the
unscrewe

Pedestal socket m

It may be
above the

Selection

- Lock th
- Establish
(460mm
- Measur

Dimension G	Pedestal socket length L
64mm (2.5in)	Std dimension
102mm (4.0in)	38mm (1.5in)
114mm (4.5in)	50mm (2.0in)
128mm (5.0in)	64mm (2.5in)
140mm (5.5in)	76mm (3.0in)
153mm (6.0in)	89mm (3.5in)

Tiller pins

For certain non-standard installations a range of tiller pins

Description	Size
Small threaded tiller pin	25mm (1in)
Extra length tiller pin	72mm (2.8in)
Extra length threaded tiller pin	72mm (2.8in)

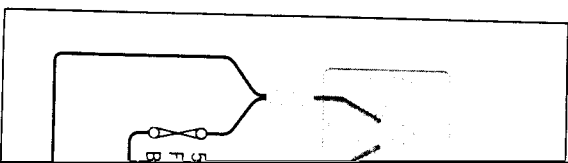
5.3 Cabling and Socket installation

The ST1000 is SeaTalk compatible receiving and transmitting to other instruments and autopilot control units via the SeaTalk cannot source power from the SeaTalk bus and therefore dedicated power supply.

Both power and data are supplied to the ST1000 via a custom plug and socket. The plug comes ready assembled and the socket is mounted in the cockpit area adjacent to the autopilot.

SeaTalk data cabling

The ST1000 is D131). It can be instrument or a the back of the



The fuse used with SeaTalk bus. Any via a separate 5A

Mounting

The socket is ass

- Fix the self adhesive location
- Carefully drill the pilot holes. Remove the plug cap
- Locate the 'O' ring socket body

Chapter 6: Functi

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6.1 Functional test

Switch on

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Operating sens

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 - course
 - Place #
 - Press +
- The hel



If it move
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Wind transducer inte

If the ST1000 the two instru

- Press the Sta
- The ST1000 s shown.

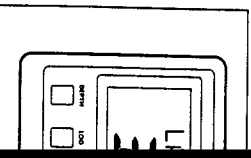


If the display c flashing 'C' the The most likely circuit or wires

SeaTalk bus

If the ST1000 bus the link car

- Push **Standby**
- Select display i autopilot contr



The ST1000 sh illumination.

If the illumination SeaTalk cabling control unit.

Keeping boat steady
control the rudder
at least 3 minutes
changes to show
Deviation and cu

15

11

Use the +1° and 1
displayed heading
known transit bear

Exit compass adju
follows:

- Push and hold **Sta**
or, to exit compas

- Push **Standby** m

Note: For installati
connected to the S
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Compass handboo

Autopilot operation

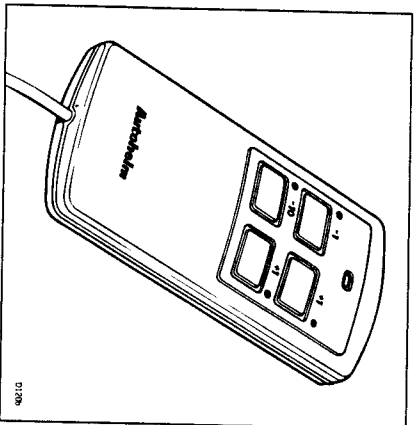
Having calibrated th
to familiarise yours

- Steer onto a comp
- Place the autopilot
- Push **Auto** to lock c
- constant heading w
- Alter course to port

Chapter 7: Accessories

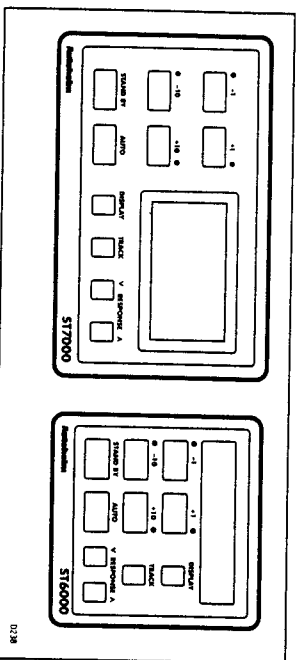
Various accessories are available for your ST1000 autopilot. These include:

- Handheld remote control (Z101)



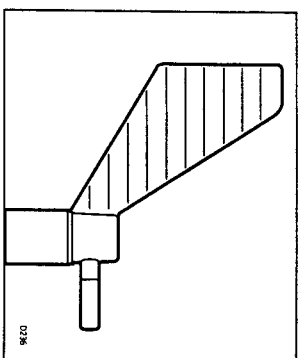
The handheld remote is supplied with 6m (20ft) of cable and a waterproof plug and socket. It allows you remote access to the four autopilot course change buttons

- Fixed control units – ST7000 (Z082), ST6000 (Z124)



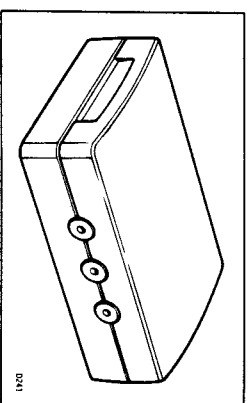
These control units are available for permanent mounting at additional positions where autopilot control is desired.

- Digital Windvane (Z087)



The digital windvane also requires the SeaTalk interface. When combined with the ST1000 these two pieces of equipment allow you to steer your boat on any course relative to an apparent wind angle.

- SeaTalk Interface (Z137)



The SeaTalk interface will convert all SeaTalk data to NMEA 0183. This allows you to feed NMEA 0183 Navigation data to a plotter or Speed and Compass NMEA information back to a position transducer for dead reckoning (Assuming the correct instruments are present on the SeaTalk bus to generate the information initially).

Chapter 8: Maintenance

- In certain conditions, condensation may appear on the unit, and can be cleared by swiping the unit with a dry cloth.
- Never use any chemical or abrasive materials on the unit. If the unit becomes dirty wipe clean with a damp cloth.

Cabling

- Avoid running cables through bilges where they will be subject to regular flexing.
- Avoid running cables close to fluorescent lighting equipment etc.
- Check cabling for chafing or damage to outer sheathings and re-secure as necessary.

Advice

Should any difficulties arise, please consult National Instruments in the U.K. or your own National Instruments representative for expert assistance.

The working parts of the drive system are sealed during manufacture and therefore do not require lubrication.

Before the unit is returned please double check that all connections are tight and that the cable is sound. Then refer to the fault finding section of this manual for advice. If the fault is not traced then please contact your nearest Autolite center for advice.

Always quote the serial number, which is printed on the underside of the autopilot.

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